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Power Transfer Enhancement in Transmission Line by Combining AC – DC Transmission

Sriram Kondiparthi Post Graduate student Gitam University **M.Praveen** Assistant Professor Gitam University **Ramu.M** Assistant Professor Gitam University I.E.S Naidu Associate Professor Gitam University

Abstract – In this paper it is possible to load the transmission lines very close to their thermal limits by allowing the conductors to carry usual ac along with dc superimposed on it. The added dc power flow does not cause any transient instability. This project gives the feasibility of converting a double circuit ac line into composite ac–dc power transmission line to get the advantages of parallel ac–dc transmission to improve stability and damping out oscillations. Simulation and experimental studies are carried out for the coordinated control as well as independent control of ac and dc power transmissions. No alterations of conductors, insulator strings, and towers of the original line are needed.

Index Terms – Extra high voltage (EHV) transmission, flexible ac transmission system (FACTS), simultaneous ac-dc power transmission

I. INTRODUCTION

IN RECENT years, environmental, right-of-way, and cost concerns have delayed the construction of a new transmission line, while demand of electric power has shown steady but geographically uneven growth. The power is often available at locations not close to the growing load centers but at remote locations. The wheeling of this available energy through existing long ac lines to load centers has a certain upper limit due to stability considerations. Thus, these lines are not loaded to their thermal limit to keep sufficient margin against transient instability.

The present situation demands the review of traditional power transmission theory and practice, on the basis of new concepts that allow full utilization of existing transmission facilities without decreasing system availability and security. To achieve this is by simultaneous ac-dc power transmission in which the conductors are allowed to carry superimposed dc current along with ac current. Ac and dc power flow independently, and the added dc power flow does not cause any transient instability. Simultaneous ac-dc power transmission was first proposed through a single circuit ac transmission line.

In these proposals Mono-polar dc transmission with ground as return path was used. There were certain limitations due to use of ground as return path. Moreover, the instantaneous value of each conductor voltage with respect to ground becomes higher by the amount of the dc voltage, and more discs are to be added in each insulator string to withstand this increased voltage. In this paper, the feasibility study of conversion of a double circuit ac line to composite ac–dc line without altering the original line conductors, tower structures, and insulator strings has been presented. In this scheme, the dc power flow is point-to point bipolar transmission system. The novelty of our proposed scheme is that the power transfer enhancement is achieved without any alteration in the existing EHV ac line. The main object is to gain the advantage of parallel ac–dc transmission and to load the line close to its thermal limit.

II. SIMULTANEOUS AC - DC POWER TRANSMISSION

Fig. 1 depicts the basic scheme for simultaneous ac-dc power flow through a double circuit ac transmission line. The dc power is obtained through line commutated 12pulse rectifier bridge used in conventional HVDC and injected to the neutral point of the zigzag connected secondary of sending end transformer and is reconverted to ac again by the conventional line commutated 12-pulse bridge inverter at the receiving end. The inverter bridge is again connected to the neutral of zig-zag connected winding of the receiving end transformer. The double circuit ac transmission line carriers both three-phase ac and dc power. Each conductor of each line carries one third of the total dc current along with ac current. Resistance being equal in all the three phases of secondary winding of zig-zag transformer as well as the three conductors of the line, the dc current is equally divided among all the three phases. The three conductors of the second line provide return path for the dc current. Zig-zag connected winding is used at both ends to avoid saturation of transformer due to dc current. Two fluxes produced by the dc current $(I_d/3)$ flowing through each of a winding in each limb

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Fig.1 Basic Scheme for composite ac - dc transmission

$$P_{R}+jQ_{R}=-E_{S}^{*}E_{R}/B^{*}-A^{*}E_{R}^{2}/B^{*}$$
(4)

of the core of a zig-zag transformer are equal in magnitude and opposite in direction. So the net dc flux at any instant of time becomes zero in each limb of the core. Thus, the dc saturation of the core is avoided. A high value of reactor X_d is used to reduce harmonics in dc current.

In the absence of zero sequence and third harmonics or its multiple harmonic voltages, under normal operating conditions, the ac current flow through each transmission line will be restricted between the zigzag connected windings and the three conductors of the transmission line. Even the presence of these components of voltages may only be able to produce negligible current through the ground due to high value of Xd.

Assuming the usual constant current control of rectifier and constant extinction angle control of inverter, the equivalent circuit of the scheme under normal steady-state operating condition is given in Fig. 2. The dotted lines in the figure show the path of ac return current only. The second transmission line carries the return dc current I_d , and each conductor of the line carries $I_d/3$ along with the ac current per phase.

 V_{dro} and V_{dio} are the maximum values of rectifier and inverter side dc voltages and are equal to $(3\sqrt{2}/\Pi)$ times converter ac input line-to-line voltage. R, L, and C are the line parameters per phase of each line. R_{cr} , R_{ci} are commutating resistances, and α , γ are firing and extinction angles of rectifier and inverter, respectively.

Neglecting the resistive drops in the line conductors and transformer windings due to dc current, expressions for ac voltage and current, and for active and reactive powers in terms of A, B, C, and D parameters of each line may be written as

$$E_{s} = AE_{R} + BI_{R}$$
(1)
$$I = CE_{s} + DI_{s}$$
(2)

$$P_{s} = CE_{R} + DR_{R}$$
 (2)
 $P_{s} + jQ_{s} = -EsE_{R}^{*}/B^{*} + D^{*}E_{R}^{2}/B^{*}$ (3)

$$V_{d_{1}}Cos\alpha \stackrel{=}{=} \underbrace{K_{cr}}_{R_{cr}} \underbrace{V_{d_{1}}Cos\gamma}_{L_{s}} \underbrace{K_{g}}_{R_{cr}} \underbrace{C/2}_{L_{s}} \underbrace{K_{g}}_{L_{s}} \underbrace{V_{d_{1}}Cos\gamma}_{L_{s}} \underbrace{K_{g}}_{R_{cr}} \underbrace{V_{d_{1}}Cos\gamma}_{L_{s}} \underbrace{K_{g}}_{L_{s}} \underbrace{V_{d_{1}}Cos\gamma}_{L_{s}} \underbrace{K_{g}}_{L_{s}} \underbrace{K_{g}} \underbrace{K_{g}} \underbrace{K_{g}} \underbrace{K_{g}} \underbrace{K_{g}}_{L_{s}} \underbrace{K_{g}} \underbrace{K_{g}}$$

Neglecting ac resistive drop in the line and transformer, the dc power P_{dr} and P_{di} of each rectifier and inverter may be expressed as

$$P_{dr} = V_{dr} I_d \tag{5}$$

$$\mathbf{P}_{\mathrm{di}} = \mathbf{V}_{\mathrm{di}}\mathbf{I}_{\mathrm{d}} \tag{6}$$

Reactive powers required by the converters are

$Q_{dr} = P_{dr} \tan \theta_r$	(7)
$Q_{di} = P_{di} \tan \theta_i$	(8)
$\cos\theta_r = [\cos\alpha + \cos(\alpha + \mu_r)]/2$	(9)
$\cos\theta_i = [\cos\gamma + \cos(\gamma + \mu_i)]/2$	(10)

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 μ_r and μ_i are commutation angles of inverter and rectifier, respectively, and total active and reactive powers at the two ends are

Transmission loss for each line is

$$P_{L}=(P_{s}+P_{dr}) - (P_{R}+P_{di})$$
 (13)

 I_a being the rms ac current per conductor at any point of the line, the total rms current per conductor becomes

$$I = [I_a^2 + (I_d/3)^2]^{1/2}$$

Power loss for each line = $P_L \approx 3I^2 R$

The net current I in any conductor is offseted from zero. In case of a fault in the transmission system, gate signals to all the SCRs are blocked and that to the bypass SCRs are released to protect rectifier and inverter bridges. The current in any conductor is no more offseted. Circuit breakers (CBs) are then tripped at both ends to isolate the faulty line. CBs connected at the two ends of transmission line interrupt current at natural current zeroes, and no special dc CB is required.

Now, allowing the net current through the conductor equal to its thermal limit (I_{th}) .

$$I = [I_a^2 + (I_d/3)^2]^{1/2}$$
(14)

Let V_{ph} be per-phase rms voltage of original ac line. Let $V_{ph also}$ V_a be the per-phase voltage of ac component of composite acdc line with dc V_d voltage superimposed on it. As insulators remain unchanged, the peak voltage in both cases should be equal

$$V_{\text{max}} = \sqrt{2}V_{\text{ph}} = V_{\text{d}} + \sqrt{2}V_{\text{a}} \tag{15}$$

Electric field produced by any conductor possesses a dc component superimpose on it a sinusoidally varying ac component. However, the instantaneous electric field polarity changes its sign twice in a cycle if $(V_d/V_a < \sqrt{2})$ is insured. Therefore, higher creep age distance requirement for insulator discs used for HVDC lines are not required.

Each conductor is to be insulated for V_{max} , but the line-to line voltage has no dc component and $V_{LL\mbox{ max}} = \sqrt{6}V_a$. Therefore, conductor-to-conductor separation distance of each line is determined only by rated ac voltage of the line.

Allowing maximum permissible voltage offset such that the composite voltage wave just touches zero in each every cycle;

$$V_{d=} V_{ph} / \sqrt{2} \text{ and } V_{a} = V_{ph} / 2 \tag{16}$$

The total power transfer through the double circuit line before conversion is as follows:

P' total
$$\approx 3 V_{\rm ph}^{2} \sin \delta_{\rm l} / X$$
 (17)

Where X is the transfer reactance per phase of the double circuit line, δ_1 and is the power angle between the voltages at the two ends. To keep sufficient stability margin, δ_1 is generally kept low for long lines and seldom exceeds 30°. With the increasing length of line, the loadability of the line is decreased. An approximate value of δ_1 may be computed from the loadability curve by knowing the values of surge impedance loading (SIL) and transfer reactance X of the line

$$P' \text{ total} = 2.M.SIL \tag{18}$$

Where M is the multiplying factor and its magnitude decreases with the length of line. The value of M can be obtained from the loadability curve.

The total power transfer through the composite line

$$P_{\text{total}} = P_{\text{ac}} + P_{\text{dc}} = 3 V_a^2 \sin \delta_2 / X + 2V_d I_d$$
(19)

The power angle δ_2 between the ac voltages at the two ends of the composite line may be increased to a high value due to fast controllability of dc component of power. For a constant value of total power, P_{ac} may be modulated by fast control of the current controller of dc power converters.

Approximate value of ac current per phase per circuit of the double circuit line may be computed as

$$I_a = V \left(\sin \delta/2 \right) / X \tag{20}$$

The rectifier dc current order is adjusted online as

$$I_{d} = 3\sqrt{I_{th}}^{*2} - I_{a}^{*2}$$
(21)

Preliminary qualitative analysis suggests that commonly used techniques in HVDC/AC system may be adopted for the purpose of the design of protective scheme, filter, and instrumentation network to be used with the composite line for simultaneous ac-dc power flow. In case of a fault in the transmission system, gate signals to all the SCRs are blocked and that to the bypass SCRs are released to protect rectifier and inverter bridges. CBs are then tripped at both ends to isolate the complete system. A surge diverter connected between the zig-zag neutral and the ground protects the converter bridge against any over voltage.

III. DESCRIPTION OF THE SYSTEM MODEL

The network depicted in Fig. 1 was studied in which a synchronous machine is feeding power to infinite bus via a double circuit, three-phase, 400-KV, 50-Hz, 450-Km ac transmission line. The 2750-MVA (5 550), 24.0-KV synchronous machine is dynamically modeled, a field coil on d-axis and a damper coil on q-axis, by Park's equations with the frame of reference based in rotor. It is equipped with an IEEE type

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Fig.3 IEEE type AC4A Excitation system



Fig.4 Master Current Controller

AC4A excitation system of which block diagram is shown in Fig.3. Transmission lines are represented as the Bergeron model. It is based on a distributed LC parameter traveling wave line model, with lumped resistance. It represents the L and C elements of a PI section in a distributed manner (i.e., it does not use lumped parameters). It is roughly equivalent to using an infinite number of PI sections, except that the resistance is lumped (1/2 in the middle of the line, 1/4 at eachend). Like PI sections, the Bergeron model accurately represents the fundamental frequency only. It also represents impedances at other frequencies, except that the losses do not change. The converters on each end of dc link are modeled as line commutated two six- pulse bridge (12-pulse), Their control system consist of constant current (CC) and constant extinction angle (CEA) and voltage dependent current order limiters (VDCOL) control. The converters are connected to ac buses via Y-Y and Y- converter transformers. Each bridge is a compact power system computer-aided design representation of a dc converter, which includes a built in six-pulse Graetz converter bridge (can be inverter or rectifier), an internal phase locked oscillator (PLO), firing and valve blocking controls, and firing angle /extinction angle measurements. It also includes built in RC snubber circuits for each thyristor. The controls used in dc system are those of CIGRE Benchmark, modified to suit at desired dc voltage. Ac filters at each end on ac sides of converter transformers are connected to filter out 11th and 13th harmonics. These filters and shunt capacitor supply reactive power requirements of converters. A master current controller (MCC), shown in Fig. 4, is used to control the current order for converters. . It measures the conductor ac current, computes the permissible dc current, and produces dc current order for inverters and rectifiers.

IV. CASE STUDIES: COMPUTAIONS AND SIMULATION

A. AC Configuration Only

The loadability of Moose (commercial name), ACSR, twin bundle conductor, 400-kV, 50-Hz, 450-km double circuit line has been computed.

The parameters of the line are

 $z = 0.03252+j0.33086\Omega/km/ph/ckt$ $y = j3.33797*10^{-6}S/km/ph/ckt$

Current carrying capacity of each sub conductor =0.9kA.

 $I_{th} = 1.8 kA/ckt.SIL = 511 MW/ckt.$

M=1.1,(from loadability curve=74.4435 Ω /ph. Using (17)–(20), the computed power at receiving end and conductor current is

$$P'_{total} = 1124.2 \text{MW}; \delta_1 \approx 30^0$$

I_{ph/ckt} = 0.803 kA

SIMULINK MODEL



Fig.6 Simulation Diagram

TABLE I COMPUTED RESULTS

Power Angle (δ) Degrees	30°	45°	60°	75°	80°
ac power(MW) = $3V_a^2 \sin \delta_2 / X$	290	410	502.61	560.6	571.55
ac current I _a (kA) I _a = V(Sin\delta/2)/X	0.4166	0.6122	0.805	0.98	1.035
dc Current (kA) I _d = $3\sqrt{I_{th}^{*2} - I_a^{*2}}$	5.253	5.078	4.829	4.529	4.418
Dc Power P _{dc} =2Vdi x Idi (MW)	1684.8	1624.9	1545.5	1149.44	1413.76
P _{total} =P _{ac} +P _{dc} (MW)	1971	2034	2048	2010	1985

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TABLE II SIMULATED RESULTS

Power Angle	30 ⁰	45°	60°	75°	80 ^e
(δ)					
Ps (MW)	2306	2371.0	2381.3	2342.0	2318.380
Pac (MW) Transfer	294.89	411.00	495.3	541.86	548.43
Pdc (MW) Transfer	1715.5	1657.0	1585.8	1498.5	1467.0
Pac_loss (MW)	11.94	30.30	54.08	81.94	91.73
Pdc_loss(MW)	280.51	265.88	241.17	217.61	208.53
Ploss_total(MW)	292.45	296.18	295.25	299.55	300.26
Pr (MW) Total Transfer	1988.8	2051.14	2062.0	2019.36	1995.00
Qs_line (MVAR)	-13.78	69.98	185.58	325.12	375.35
Qr_line (MVAR)	39.08	146.84 0	280.85	431.96	484.38
Qrec (MVAR)	883.6	884.36	885.29	878.1	869.48
Qinv (MVAR)	841.3	823.5	797.43	764.64	753.04
ac current Ia (kA)	0.41577	0.61123	0.79684	0.96952	1.02383
dc current Id (kA)	5.24263	5.1136	4.91185	4.6355	4.52512
Cond. dc current Id/3 (kA)	1.74754	1.70453	1.6373	1.5452	1.5084
conductor current Isim(kA)	1.78587	1.78264	1.78281	1.78641	1.78833
Increase of power transfer	76.94%	82.49%	83.451%	79.66%	77.5%

The computed and simulated results are found to be in close conformity.

The conductor current 0.805246 kA is much below the thermal limit 1.8 kA.

B. Conversion of the Conventional Double Circuit AC Line Into Composite AC-DC Power Transmission Line

Using (15) and (16)

$$V_a = 120 kV/ph (208 kV_{LL}); V_d = 160 kV$$

The above ac voltage Va has been increased from 115.473 to 120 kV, and Vd has been decreased from 163.328 to 160.0 kV to have zero crossing in voltage wave. δ_2 is assumed to be maximum 80, which is commonly used in lines controlled by FACTS devices.

The computed *approximate* power transfers for converted line at various transmission angles are shown in Table I.

The proposed composite ac-dc power scheme shown in Fig. 1 has been simulated in steady-state mode as a real system using Simulation. The power and current readings at various points on the system are tabulated in Table II.

Pdc_loss includes line loss due to dc current and converter losses. Pac_loss is line loss due to ac current only. The total power Pr at receiving end is the actual net power transfer after subtracting all losses like circuit breakers, transformers, etc.

It has been seen from computation as well as simulation that the maximum power transfer of 2062.0 MW transmitted by composite ac–dc line occurs at power angle of 60° . The same amount of power transfer through conventional double circuit line would require a power angle of 73.68, which is beyond the safe limit for power angle. The corresponding conductor current ($I_{ph/ckt}$) is 1.7744 kA.



Fig.7 Sending End & Receiving End Voltages



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Fig.8 Sending End & Receiving End Currents



Fig.9 Rectifier & Inverter DC Side Voltage, Rectifier DC side Current



Fig.10 Rectifier & Inverter DC side Current



Fig.11 Alpha Order For Rectifier & Inverter



Fig.12 Active & Reactive Power at Ps



Fig.13 Active Power at Pdc



Fig.14 Active Power at Pac



Fig.15 Active Power & reactive power at Ptotal



Fig.16 Rectifier AC side Voltage & Currents



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Fig.17 Combined AC – DC Current & AC Current to zigzag Transformer



Fig.18 Sending End Current without DC



Fig.19 Receiving End Current with DC

Fig. 7 to 19 shows the time response of various system performances at power angle of 30° .

It has been observed from above tracing that system is stable even after superimposing dc on ac.

V. EXPERIMENTAL VERIFICATION

The feasibility of the conversion of the ac line to composite ac–dc line was verified in a laboratory-size model. The basic objective was to verify the operation of the transformers, particularly, the effect on core saturation, with the superimposed ac–dc current flow and the power flow control.

The transmission line was modeled as a three-phase – network having L=83mH and C=0.5 μ F. Transformers having a rating of 6 KVA, 400/75/75 Volts were used at each end. The secondary of these transformers were connected in zig-zag fashion. A supply of 3-ph, 400 V, 50 Hz was given at the sending end and 400 V, 0–5.25 kW variable resistive load was connected at the receiving end. A 10-Amp, 23-mH dc reactor (X_d) was used at each end with the 230V zig-zag connected neutral. Two identical line-commutated six-pulse bridge converters were used for rectifier and inverter. The dc voltages of rectifier and inverter bridges were adjusted to vary dc current between 0 and 6 A. Ac filters were not connected at converter ac buses.

The power transmission with and without dc component was found to be satisfactory. There was no saturation of the transformers core with and without dc component.

VI. CONCLUSION

The feasibility to convert ac transmission line to a composite ac–dc line has been demonstrated. The line is loaded to its thermal limit with the superimposed dc current. The dc power flow does not impose any stability problem. The advantage of parallel ac–dc transmission is obtained.

Dc current regulator may modulate ac power flow. There is no need for any modification in the size of conductors, insulator strings, and towers structure of the original line.

The optimum values of ac and dc voltage components of the converted composite line are 1/2 and times the ac voltage before conversion, respectively.

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